

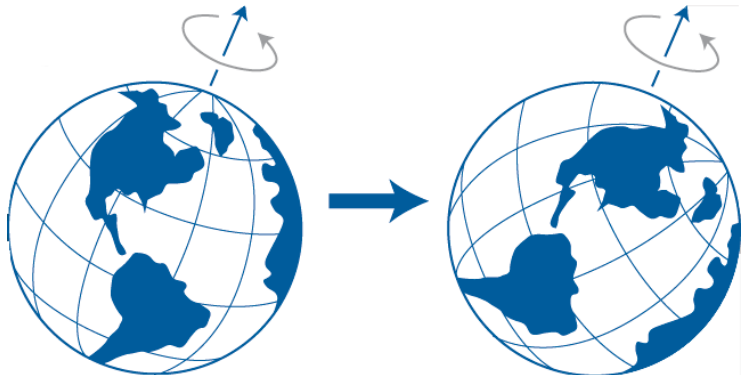
# An Introduction to the Polar Motion

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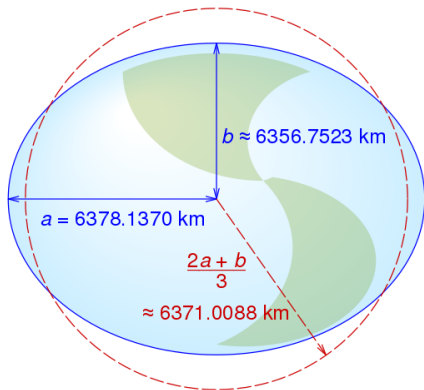
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# What is polar motion?



# TRS in rigid body approximation



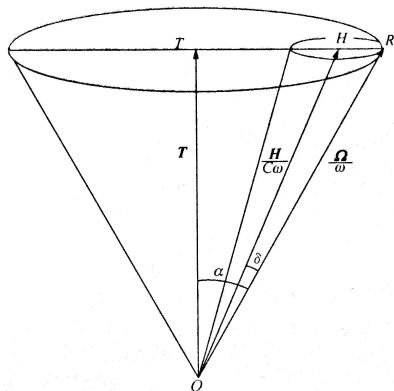
Inertia tensor of earth in TRS:

$$\mathbb{J} = \text{diag}\{A, B, C\}$$

Where  $A = B < C$

The ideal frame of ITRS is based on Tisserand mean axis.

# 3 poles of Earth



Where  $\omega = \Omega \cdot T$

- $T$  Tisserand mean pole
- $H$  Angular momentum pole
- $R$  Angular velocity pole of Earth

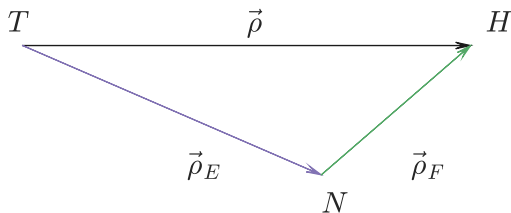
$$\alpha \approx 0.2'', \delta \approx 0.7\text{mas}$$

$$\frac{\bar{T}H}{\bar{H}R} = \frac{A}{C - A} = 304.4$$

Figure: Vector cones of Earth rotation.

# Polar motion

The polar motion is defined as position of pole H in TRS, and we adapt a polar motion vector  $\vec{\rho}$  (before H.Jeffreys,1963 & Atkinson,1975):



**Figure:** Where  $\vec{\rho}$  is polar motion,  $\vec{\rho}_E$  is free component while  $\vec{\rho}_F$  forced component, N is the CIP

# polar motion of CIP in ITRS

- **Euler period** (Assume that Earth is a rigid body):

$$\frac{2\pi}{\omega} \frac{A}{C - A} = 303.6d$$

Where  $\omega = \boldsymbol{\Omega} \cdot \boldsymbol{T}$

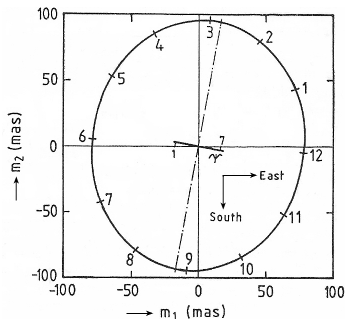
- **Chandler wobbling:**

Period:  $\tau_C = 435d$  and Amplitude :  $0.1'' - 0.2''$

Newcomb think it is Euler free polar motion with solid earth

## Annual component

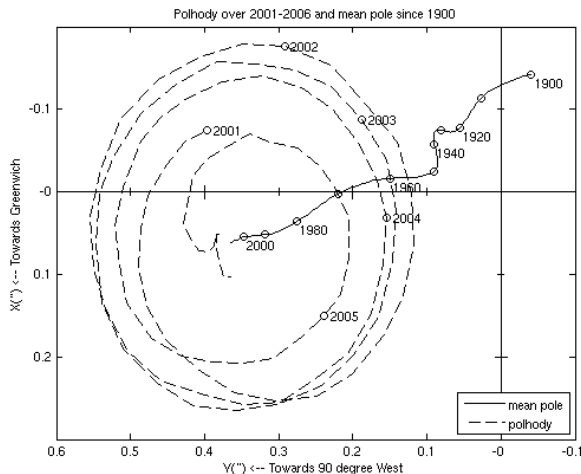
Annual component  $\mathbf{m}$  of polar motion is a forced motion excited predominantly by atmospheric dynamics. (H.Volland,1994)



$$\mathbf{m} = -\frac{\nu_C B \tilde{p}}{2} \left[ \frac{e^{i\ell\Omega_a(t-t_0)}}{\ell - \nu_C} - \frac{e^{-i\ell\Omega_a(t-t_0)}}{\ell + \nu_C} \right] e^{i\lambda_0}$$

Where  $\nu_C = 1/\tau_C = 0.83\text{yr}^{-1}$  is Chandler frequency,  $B \approx 29.0\text{mas/hPa}$ ,  $t_0 = -0.07\text{yr}$ ,  $\lambda_0 = 170^\circ$

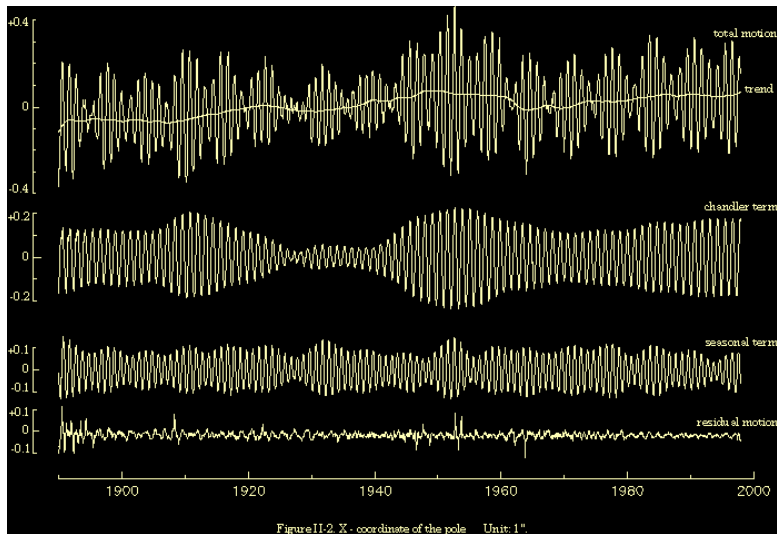
# How is polar moving?



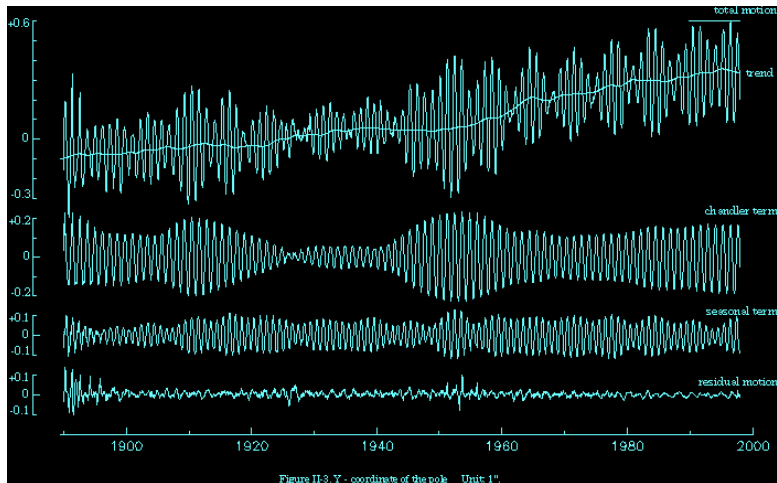
**Figure:** Polar motion 2001-2006 provided by the former Central Bureau 1st Jan. 2001.



## X component



# Y component



THANKS FOR LISTENING!